



# **BRUSHLESS DC MOTOR FAMILY**

# Series NT DYNAMO<sup>®</sup> Geared Brushless DC Permanent Magnet Motor



#### <u>Spur</u>

- Up to 600:1 Gear Ratio
- Up to 200 oz-in [1412 mN-m] of Torque
- AGMA 7 Gear Quality



- <u>Planetary</u>
  - Wide Selection of Gear Ratios and Features
  - Inline, Right Angle, and Metric
  - High Torque and Low Backlash

Some factors to consider in maximizing your application system's performance.

- Torque Multiplication
- Speed Reduction
- Inertia Matching
- Radial Loading
- Axial Loading
- Noise

<u>Spur</u> gearheads will suit most needs in relatively low-torque applications. However, spur configurations have higher backlash and are usually less efficient than planetary types of similar construction. For constant velocity and unidirectional applications where backlash is less of a concern, spur gearheads are ideal.

<u>Planetary</u> gearheads are generally specified for their high rated torque and high input speed. Planetary gearheads are more robust with higher accuracy, lower backlash, and longer life than spur gearheads. They are well suited for higher





load applications in small packages ranging from nut runners and nut setters to small medical tools, pumps, and other devices.

The gearhead solution (Spur Vs. Planetary) is primarily dependent upon the application. Some factors to be considered in making proper trade-offs between cost and performance are shown below.

DESIGN FACTORS	GEARHEAD TYPE		
DESIGN FACTORS	SPUR	PLANETARY	
Torque Capacity	Lower	Higher	
Power to Weight Ratio	Lower	Higher	
Power to Size Ratio	Lower	Higher	
Torsional Stiffness	Lower	Higher	
Backlash	Higher	Lower	
Available Number of Gear	Higher	Lower	
Ratios			
Operating Speed	Lower	Higher	
Size	Larger	Smaller	
Cost	Lower	Higher	

#### NT Dynamo BLDC Motor Specifications

- Standardized Modules
  - Brings high volume pricing to low volume orders
  - Makes product performance easy to specify
  - Ensures maximum product quality
- Flexible Performance
  - Operates from 12-48Vdc power sources
  - o Operates in speed or torque mode
  - o 4 quadrant closed loop or 2 quadrant open loop
  - Compact integrated encoder option





## **Electrical**

- Integral Motor Controls Matched to a Motor Winding
- 2 or 4 Quadrant Operation
- 10Vdc-48Vdc Range (depending on motor control)
- Up to 40 oz-in [282 mN-m] Torque (with no gearing)
- Ultra Smooth Precision Motion Quality
- Approved Class B Insulation System
- 100% Final Tested
- Custom Windings Available

#### **Mechanical**

- Long Life Ball Bearing System
- Size 17 and NEMA 23 Mounting Flange
- Neodymium Ring Magnets (not arcs)
- Stainless Steel Shaft
- Over 20,000 Hours of Design Life @ Rated Torque
- Standard Molex<sup>®</sup> Connectors
- Small Package Size with Low Rotor Inertia
- Up to 6000 RPM Operation

#### **Reliability**

- Over 1.5 Million Hours of Combined Life and Reliability Testing
- In Use at Major OEM's in Demanding Applications
- Our Proven Design can Help Reduce the Test Time Needed to Validate Your Design
- Contact Hurst for Detailed Life and Reliability Date

#### Integral Motor Control and Encoders

- External Motor Module
  - For Use with Customer Supplied Motor Control
  - Provides Hall Sensor and/or Encoder Outputs
- Analog Motor Control
  - Economical Control via a Simple Speed Pot or a 0-5Vdc Control Signal
  - PWM Motor Control
    - Control via Customer Generated PWM Signal
- Encoders 100, 250, 256 with Index Pulse, 400, or 1000 Line Resolution

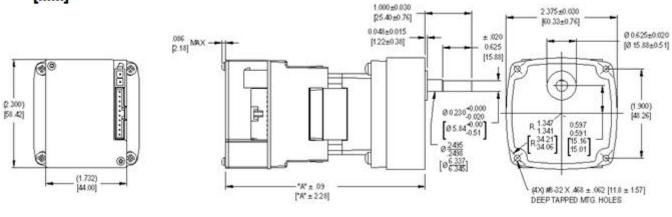




INTEGRATED CONTROL DRAWINGS

# SPUR GEAR MOUNTING

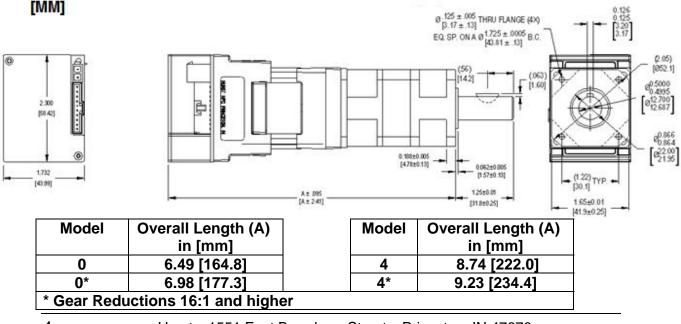
IN [MM]



Model	Overall Length (A)	
	in [mm]	
0	4.87 [123.7]	
6	7.12 [180.8]	

## SIZE 17 PLANETARY GEAR MOUNTING





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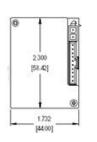
(82.95) [74.9]

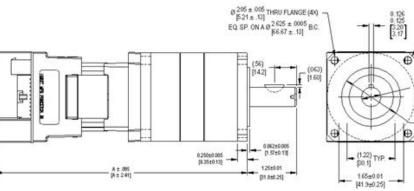
80.5000 0.4995 812.700 12.687

01.500 1.498 [038.10 [38.05]

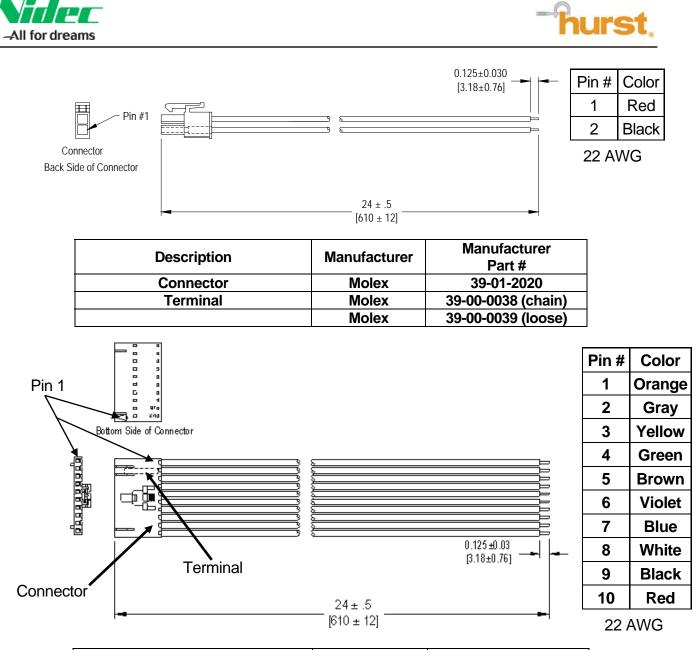
### NEMA 23 PLANETARY GEAR MOUNTING

IN [MM]





Model	<b>Overall Length</b>	Model	Overall Length
	(A) in [mm]		(A) in [mm]
0	6.68 [169.7]	4	8.93 [226.8]
0*	7.50 [190.5]	4*	9.75 [247.7]
* Gear Reductions 16:1 and higher			



Description	Manufacturer	Manufacturer Part #
Connector	Molex	50-57-9410
Terminal	Molex	16-02-0087 (chain)
	Molex	16-02-0103 (loose)

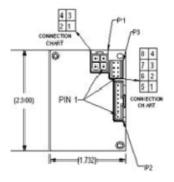
Minimum Gauge Size is recommended to be 22 AWG or greater.

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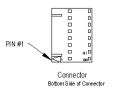
## EXTERNAL CONTROL DRAWINGS

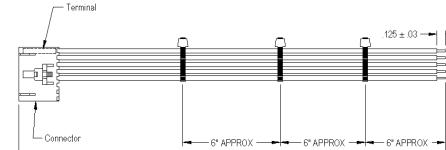


HALL CONNECTIONS (P2)			POWER	CONNECTIONS (P1)	
PIN #	DESCRIPTION	PIN #	DESCRIPTION	PIN #	DESCRIPTION
1	Vs	5	HALL C	1	PHASE C
2	Vs (return)	6	BLANK	2	PHASE B
3	HALL B	7	BLANK	3	PHASE A
4	HALL A	8	BLANK	4	FRAME GROUND
	ENCODER CONNECTIONS (P3)				
1	+5Vs	4	N/C	7	/B
2	A	5	+5Vs (return)	8	N/C
3	В	6	/A		



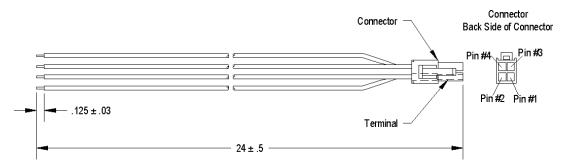






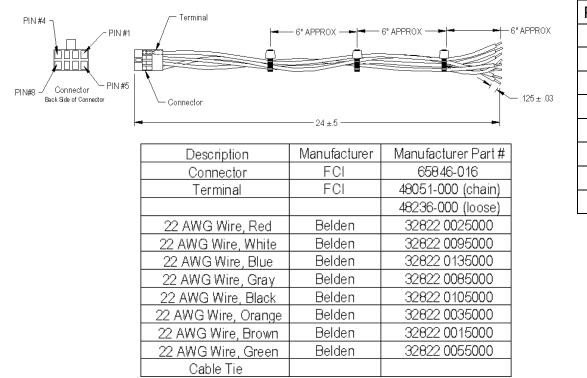
Pin #	Color
1	Red
2	Black
3	Brown
4	White
5	Green

	24 ± .5	
Description		Maria factoria Dast V
Description	Manufacturer	Manufacturer Part #
Connector	Molex	50-57-9408
Terminal		16-02-0087 (chain)
		16-02-0103 (loose)
22 AWG Wire, Red	Belden	32822 0025000
22 AWG Wire, Black	Belden	32822 0105000
22 AWG Wire, Brown	Belden	32822 0015000
22 AWG Wire, White	Belden	32822 0095000
22 AWG Wire, Green	Belden	32822 0055000
Cable Tie		



Pin #	Color
1	Red
2	Black
3	White
4	Green

Description	Manufacturer	Manufacturer P/N
Connector	Molex	39-01-2040
Terminal	Molex	39-00-0038 (chain)
		39-00-0039 (loose)
22 AWG Wire, Red	Belden	32822 0025000
22 AWG Wire, Black	Belden	32822 0105000
22 AWG Wire, White	Belden	32822 0095000
22 AWG Wire, Green	Belden	32822 0055000



Pin #	Color
1	Red
2	White
3	Blue
4	Gray
5	Black
6	Orange
7	Brown
8	Green

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# NOTICE

Minimum Gauge Size is recommended to be 22 AWG or greater.

Vider

All for dreams